

Overview

Conference Program

	1. IOT & CONNECTIVITY				2. EMBEDDED OS		3. SAFETY & SECURITY
DAY 1: morning	Session 1.1 Industrial IoT 1 Room Prag	Session 1.10 Intelligent IoT Room Budapest			Session 2.1 Developing with Zephyr: Introduction Room St. Petersburg		Session 3.1 Trustworthy Embedded Devices Room Istanbul
DAY 1: afternoon	Session 1.2 Industrial IoT 2 Room Prag	Session 1.11 OPC UA Use Cases Room Budapest			Session 2.2 Developing with Zephyr: How to Room St. Petersburg		Session 3.2 Implementing the Cyber Resilience Act (CRA) Room Istanbul
	Session 1.3 Localization & Tracking Room Prag	Session 1.12 Vehicular Networks Room Budapest			Session 2.3 Zephyr for Safety & Security Applications Room St. Petersburg		Session 3.3 Security in the Quantum Era Room Istanbul
DAY 2: morning	Session 1.4 TSN for Industrial Automation Room Prag	Session 1.13 Cellular IoT: 5G & 6G Room Budapest			Session 2.4 Developing with Embedded Linux Room St. Petersburg		Session 3.4 Qualifying Safe Embedded Systems Room Istanbul
DAY 2: afternoon	Session 1.5 TSN Management Room Prag	Session 1.14 Cellular IoT: Emerging technologies Room Budapest			Session 2.5 Real-time Linux Room St. Petersburg		Session 3.5 Efficient Engineering of Safety/Security Projects 1 Room Istanbul
	Session 1.6 TSN Synchronization Room Prag	Session 1.15 Mesh Networks Room Budapest			Session 2.6 Yocto Use Cases Room St. Petersburg		Session 3.6 Efficient Engineering of Safety/Security Projects 2 Room Istanbul
DAY 3: morning	Session 1.7 Fieldbus Applications Room Prag	Session 1.16 Bluetooth Technologies Room Budapest	Session 1.19 IoT Identify Management Room Riga	Session 1.22 Modular & Open Systems Room Copenhagen	Session 2.7 Optimization of Embedded OS Room St. Petersburg		Session 3.7 Developing Safe Software Room Istanbul
	Session 1.8 Fieldbus Security Room Prag	Session 1.17 Bluetooth Channel Sounding Room Budapest	Session 1.20 IoT Security Management Room Riga		Session 2.8 Over The Air (OTA) Updates Room St. Petersburg		Session 3.8 The Way to Safe AI Room Istanbul
DAY 3: afternoon	Session 1.9 CAN: Protocols & Security Room Prag	Session 1.18 Wireless Connectivity with Matter & Thread Room Budapest	Session 1.21 IoT Data Management Room Riga		Session 2.9 Virtualization: Hypervisors & Containers Room St. Petersburg	Session 2.10 Embedded OS in Automotive Applications Room Krakau	Session 3.9 Safety & Security Use Cases Room Istanbul

Conference Fees

Fees Classes	Full Price
1 Half-Day Class Ticket	EUR 495.00
2 Half-Day Classes Ticket	EUR 990.00
3 Half-Day Classes Ticket	EUR 1295.00
4 Half-Day Classes Ticket	EUR 1490.00
5 Half-Day Classes Ticket	EUR 1795.00
6 Half-Day Classes Ticket	EUR 1990.00

Fees Sessions	Full Price
Sessions 1 Day Ticket	EUR 695.00
Sessions 2 Day Ticket	EUR 845.00
Sessions 3 Day Ticket	EUR 990.00

All fees excluded 19% VAT

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4. HARDWARE DESIGN		5. SOFTWARE & SYSTEMS ENGINEERING		6. EMBEDDED VISION	7. EDGE AI
Session 4.1 CPUs & Coprocessors Room Oslo	Session 4.4 MIPI I3C Serial Bus Room Krakau	Session 5.1 Programming Languages Room Kiew	Session 5.10 Embedded DevOps and CI Room Riga		Session 7.1 Compliance for Edge AI Room Kopenhagen
Session 4.2 Multiprocessor System Design Room Oslo		Session 5.2 Programming Languages: Rust Room Kiew	Session 5.11 Open Source Software Room Riga	Session 6.1 MIPI for Embedded Vision Room Krakau	Session 7.2 Workflows for Edge AI Room Kopenhagen
Session 4.3 Developing with FPGAs Room Oslo	Session 4.5 MIPI Interfaces Room Krakau	Session 5.3 Software Coding Paradigms Room Kiew	Session 5.12 Development Processes for SW-Defined Vehicles (SDV) Room Riga		Session 7.3 Strategies for Building Edge AI Room Kopenhagen
Session 4.6 RISC-V Development Ecosystem Room Oslo		Session 5.4 Robust Software Architectures Room Kiew	Session 5.13 Test Processes and Strategies Room Riga	Session 6.2 Embedded Vision Use Cases Room Krakau	Session 7.4 Hardware for Edge AI Room Kopenhagen
Session 4.7 RISC-V System Design Room Oslo		Session 5.5 Artificial Intelligence (AI) Algorithms Room Kiew	Session 5.14 Software Product Quality Room Riga	Session 6.3 AI in Embedded Vision Applications Room Krakau	Session 7.5 Frameworks for Edge AI Room Kopenhagen
Session 4.8 Memory: Test for Zero Defect Room Oslo		Session 5.6 Debugging Software & Systems Room Kiew	Session 5.15 Test Automation Room Riga	Session 6.4 Embedded Vision Interfaces Room Krakau	Session 7.6 Smart Sensing Based on Edge AI Room Kopenhagen
Session 4.9 Developing Embedded Hardware Room Oslo	Session 4.11 Measuring Power Supply Current Room Krakau	Session 5.7 MISRA SW Coding Guidelines Room Kiew			
Session 4.10 Sensors, Actuators, Radar Room Oslo	Session 4.12 Ultra Low Power & Energy Harvesting Room Krakau	Session 5.8 Static Code Analysis Room Kiew			Session 7.7 Edge AI Case Studies 1 Room Kopenhagen
		Session 5.9 How to Leverage AI for Development Room Kiew			Session 7.8 Edge AI Case Studies 2 Room Kopenhagen



STEERING BOARD

(from left to right):
 Prof. Dr. Dirk Pesch,
 Dr. Bernd Hense,
 Caspar Grote,
 Prof. Dr. Axel Sikora,
 Prof. Dr. Peter Fromm,
 Prof. Dr. Ansgar Meroth.

The steering board is the strategic think tank behind the embedded world Conference. Currently six senior engineers with excellent scientific and business records, with open minds and a lot of ideas, shape the future direction of the embedded world Conference.


The photo was taken at the Hochschule Offenburg, Germany.

	1. IOT & CONNECTIVITY	2. EMBEDDED OS	3. SAFETY & SECURITY
10:00-10:15	Opening & Welcome Remarks Room Tokio Prof. Dr. Axel Sikora, Hochschule Offenburg/Hahn-Schickard		
10:15-10:45	Conference Keynote: Pushing Boundaries: Flexible AI at the Edge Sandra Rivera, Altera		
	1.1: Industrial IoT 1	1.10: Intelligent IoT	2.1: Developing with Zephyr: Introduction 
11:00-11:30	How Can Connectivity Innovations Transform the Industrial Market? Jonathan Regalado-Hawkey, Valens Semiconductor	Intelligently Online When Needed: A Revolution in IoT Cellular Connectivity! Thomas Larsson, Giesecke+Devrient Mobile Security Germany	What's in a Name: Is Zephyr Really (Just) an RTOS? Benjamin Cabé
11:30-12:00	Unlocking Value and Driving Innovation: The Power of IoT in Manufacturing Marc Sauter, Vodafone Business IoT	How to Get from Sensor Data to an AI Based Realtime Application – A Technical Deep Dive Simon Kneller, esentri	Unlocking Streamlined Development and Simplifying Maintenance with Zephyr RTOS for IoT Devices Luka Mustafa, IRNAS
12:00-12:30	A Visionary Modelling Approach for Predictive Maintenance in a Highly Regulated Environment Peter Lieber, SparxSystems Software	Edge AI Unleashed: Architecting Seamless Cloud-to-Edge Intelligence with Connected Services Channa Samynathan, Amazon Web Services	Boosting Product Development with the Zephyr RTOS – A Critical Reflection Moritz Marquardt, Carl Zeiss
12:30-12:45	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A
Lunch Break			
	1.2: Industrial IoT 2	1.11: OPC UA Use Cases	2.2: Developing with Zephyr: How to 
13:45-14:15	Built to Last: Critical Considerations for Future-Ready IoT Toby Gasston, Wireless Logic	OPC UA at Field Level with Open Source Solutions Vasilij Strassheim, Linutronix	Unlocking Zephyr's Potential: A Practical Guide to Efficient Product Development Dr. Tobias Kästner, inovex
14:15-14:45	Digital Product Passport as Key Enabler of Circular Economy Ricardo Dunkel, Open Industry 4.0 Alliance	LADS OPC UA – Enabling Plug'n'Play Connectivity for Laboratory and Analytical Devices Dr. Melanie Kahl, infoteam Software	From Code to Current: Reducing Energy Consumption in Zephyr Device Drivers Fabian Pflug, grandcentrix
14:45-15:15	Integrating Edge and Cloud: Technical Comparison and Performance Benchmarking of DDS, OPC UA, MQTT, and Kafka Dr. Gerardo Pardo, Real-Time Innovations (RTI)	Time Sensitive Networking for Industrial Automation using OPC-UA Martin Kellermann, Microchip Technology	Porting a Bluetooth Application to Zephyr OS – Benefits and Challenges Dr. David Egan, Infineon Technologies
15:15-15:30	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A
Coffee Break			
	1.3: Localization & Tracking	1.12: Vehicular Networks	2.3: Zephyr for Safety & Security Applications 
16:00-16:30	AI-Driven Dynamic Multiprotocol Integration for Enhanced IoT Connectivity and Localization Dr. Wael Guibene, Silicon Labs	The Emerging Importance of Connected V2X Mobility for Safety on Roads Thomas Jaeger, DEKRA SE	Preparing for the CRA when using Open Source Projects Kate Stewart, Linux Foundation
16:30-17:00	Is Tracking the Killer App for IoT? Incorporating Find My Functionality into Bluetooth Devices Dr. David Egan, Infineon Technologies	Vehicle Communication System in Distributed Data Space Matija Bedeković, Cetitec	Zephyr as a Secure Choice for Embedded Development Pierre Lecomte, Witekio
17:00-17:30	HD-FDD and the Art of Seamless Asset Tracking Igor Tovberg, Sony Semiconductor Israel	Applying TSN and DDS to Software Defined Vehicles and Other Real-time Edge Applications Dr. Gerardo Pardo, Real-Time Innovations (RTI)	Testing Embedded Software With Zephyr Mohammed Billoo, MAB Labs Embedded Solutions
17:30-17:45	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A
			3.1: Trustworthy Embedded Devices
			3.2: Implementing the Cyber Resilience Act (CRA)
			3.3: Security in the Quantum Era


4. HARDWARE DESIGN	4. HARDWARE DESIGN	5. SOFTWARE & SYSTEMS ENGINEERING	5. SOFTWARE & SYSTEMS ENGINEERING	6. EMBEDDED VISION	7. EDGE AI
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Opening & Welcome Remarks | Room Tokio
 Prof. Dr. Axel Sikora, Hochschule Offenburg/Hahn-Schickard


Conference Keynote: Pushing Boundaries: Flexible AI at the Edge
 Sandra Rivera, Altera

4.1: CPUs & Coprocessors	4.4: MIPI I3C Serial Bus 	5.1: Programming Languages	5.10: Embedded DevOps and CI	7.1: Compliance for Edge AI
Processing and Power Subsystem Co-development for Sustainable and Cost Effective Time to Market Juan Romero, NXP Semiconductors	An Introduction to MIPI I3C, the Next-Generation Serial Bus Enabling Industrial Applications Michele Scarlatella, MIPI Alliance	Making C++ Safe – or Better go Rust, C# or Cpp2? Klaas van Gend, Sioux Technologies	Embedded DevOps: Hardware in the CI Loop and the Transformative Power of Sharing Work-in-Progress Darwin Sanoy, GitLab	Law Compliance of AI Systems Prof. Dr. Julius Schöning, Osnabrück University of Applied Sciences
Designing Domain Specific Accelerators with High-Level Synthesis Prof. Russell Klein, Siemens EDA	Best Practices for Smooth Adoption of the MIPI I3C Interface Martin Cavallo, Binho LLC	Rust Embedded Ecosystem: An Overview Tamme Dittrich, Tweede golf	Toward Continuous Firmware Delivery Guilherme Costa, Stratio Automotive	Qualification of AI/ML Systems and Interfacing Devices Steve Di Camillo, LDRA
Mastering the Art of Microcontroller Selection for IoT and Edge Computing Innovations: A Deep Dive Sakshi Madaan, Anders Electronics	Enabling Next-Generation Embedded Vision Systems with MIPI I3C Marie-Charlotte Leclerc, STMicroelectronics	Embedded MicroPython: Viable and Surprisingly Capable for IoT and Embedded Systems Brad Stewart, AeroSynth	DevSecOps for Linux-Based MPUs Laurent Sustek, STMicroelectronics	Design, Exploration and Evaluation of Safety-Critical Software for Integrating AI/ML-based Algorithms Dr. Gabriel Pedroza, Ansys
Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A

Lunch Break

4.2: Multiprocessor System Design	5.2: Programming Languages: Rust	5.11: Open Source Software	6.1: MIPI for Embedded Vision 	7.2: Workflows for Edge AI
Enhance the Software Developer Experience in Semiconductor Industry Dr. Stefano Mangioni, Accenture	Rust in Embedded Systems: Safe and Efficient Programming for the Next Generation of IoT Devices Joseph Schneider, Dojo Five	Enabling Software Defined Vehicles through Open Source Software Dan Cauchy, Automotive Grade Linux	Empowering Autonomous Driving: The Impact of MIPI CSI-2 on Advanced Sensor Technologies Simon Bussieres, Rambus	AI-Powered Workflow Automation: Autonomous Service Labeling and RAG Systems Dr. Philipp Dumbach, infoteam Software
How Many CPUs is too Many? Hugh Breslin, Microchip Technology	Using Rust with Existing Systems Dion Dokter, Tweede golf	Enabling Safety in the SDV with Open-Source Software Dr. Alexander Mattausch, Elektrobit Automotive	Machine Vision Processing of Event-based Sensor with MIPI Interface on FPGAs Satheesh Chellappan, Lattice Semiconductor	Leveraging Automated AI Model Discovery and Development for Edge Processing Ali Osman Ors, NXP Semiconductors
Network Traffic Tunneling on Heterogenous SoCs Nitika Verma, Texas Instruments	Rust for Medical Device Development Milica Kostic, Zuhlke Engineering	Open-source GPU Drivers: Why you need them for your Embedded Products Samuel Iglesias Gonsálvez, Igalia	Addressing the Challenges in the Medical Industry's Transition to Disposable Endoscopes Jonathan Regalado-Hawkey, Valens Semiconductor	Tackling ML Performance Challenges In Multichannel Edge Environments David Steele, Arcturus
Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A

Coffee Break

4.3: Developing with FPGAs	4.5: MIPI Interfaces 	5.3: Software Coding Paradigms	5.12: Development Processes for SW-Defined Vehicles (SDV)	7.3: Strategies for Building Edge AI
Enhancing Workflow of FPGA Development through Container Orchestration Jonathan Hendriks, Zuhlke Engineering	Genius in Simplicity: A Practical Guide to Connecting DSI-2 Display Panels to Microcontrollers in Embedded Applications Dr. Mohamed Hafed, Introspect Technology	Low-Latency Embedded Applications: Optimizing for Speed and Responsiveness Ofra Bechor, Green Hills Software	Rapid Prototyping for Software-Defined Vehicles with GenAI and the digital.auto Playground Prof. Dr. Dirk Slama, Bosch	Contextual AI and the Creation of Efficient On-Device Assistants Dominic Pajak, Synaptics
Hybrid Verification Approaches for Large-scale FPGA-based SoCs Moumon Chatterjee, Ericsson	How Universal Flash Storage is Enabling Edge-AI in Automotive and Industrial Applications Bruno Trematore, KIOXIA Europe (Speaking on Behalf of MIPI Alliance and JEDEC)	Understanding "Memory Safety": Guarantees, Limits, and Different Solution Approaches Dr. Martin Becker, The MathWorks	Solving the Complexities behind Software Integration for SDVs Salvador Rodriguez Lopez, TTTech Auto	How to Bridge Technological Gaps in Edge AI Industrial Applications Umar Ahmad, Advantech Europe
From Breadboard to FPGA Pablo Trujillo, controlpaths	Soundwire When Compared to I2S and TDM Saravana Kumar Muthusamy, Soliton Technologies	Typedefs and Records and Generics, oh my: New Type Safety Features Coming in C2Y Alex Celeste, Perforce Software	How Continuous Integration is Transforming the Automotive Industry Philip Miesbauer, Jaguar Land Rover	How to Run Big AI Models Using NVIDIA TAO on the Latest CortexM85 ARM Based MCU's Amir Sherman, Edge Impulse
Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A

Want more? See page 7 for additional classes!

	1. IOT & CONNECTIVITY		2. EMBEDDED OS		3. SAFETY & SECURITY
	1.4: TSN for Industrial Automation	1.13: Cellular IoT: 5G & 6G 	2.4: Developing with Embedded Linux		3.4: Qualifying Safe Embedded Systems
10:00-10:30	Keys to Scaling Time-Sensitive Networks and vPLCs for Mass Adoption of Industry 4.0 Christopher Main, TenAsys	Reality Check 5G IoT: Revolution Delayed? Peter Gaspar, A1 Digital International	The Status of Debian for Embedded Systems Leonardo Held, Toradex		Successful SIL4 Project thanks to HIL Testing During Development Michael Weiß, Hitex
10:30-11:00	TSN-based Factory Backbone as an Enabler for vPLCs Philipp Neher, University of Stuttgart	Seamless Transitions between Terrestrial and Satellite Networks in IoT Systems Marco Guadalupi, Sateliot	Porting an Embedded Linux Driver from C to Rust Remo Senekowitsch, ZHAW Institute of Embedded Systems		Level up your Embedded Testing Game – Fretish, Robot and Twister: A Dream Team Christian Schlotter, Carl Zeiss Meditec
11:00-11:30	DetNet: How Industrial Automation Benefits from Cloud and Internet Technologies Dr. Florian Kauer, Linutronix	Green FPGA: The Role of FPGA in Waveform Agnostics Radio Unit (RU) for 5G and 6G Applications Dr. Hossam Fattah, Lattice Semiconductor	Running Sandboxed Programs in the Linux Kernel – Practical Use-cases for eBPF Jan Altenberg, Open Source Automation Development Lab (OSADL)		Task Monitoring Unit for Temporal and Logical Flow Measurement in Safety Critical Automotive Microcontroller Units Giuseppe Dangelo, STMicroelectronics
11:30-11:45	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A		Discussion/Q&A
Lunch Break					
	1.5: TSN Management	1.14: Cellular IoT: Emerging technologies 	2.5: Real-time Linux		3.5: Efficient Engineering of Safety/Security Projects 1
12:45-13:15	Enabling Intent-based Network Management for TSN by Modelling Complex Dependencies Hamza Chahed, Karlstad University	GCF Certification for Emerging IoT Cellular Technologies: 5G RedCap and NTN NB-IoT Carlos Pedraz Rodriguez, Global Certification Forum	Evolving IoT Patterns in Heterogeneous Multicore for Linux Real-Time (RT) Richard Elberger, Amazon Web Services		Dangers of Over-Engineering a Safe System Louay Abdelkader, BlackBerry QNX
13:15-13:45	Ensuring Reliable TSN Management by Monitoring Time Synchronization Precision Kedar Dnyaneshwar Naik, Hochschule Offenburg	SGP.32: Advancing Remote SIM Provisioning for the IoT Bertrand Moussel, Trusted Connectivity Alliance	Real Time Networking with PREEMPT_RT Kurt Kanzenbach, Linutronix		How Much Safety Can You 'Buy' for Less than a Dollar? Maria Teresa Jacob, Microchip Technology
13:45-14:15	Analyzing and Solving Common Interoperability Challenges in TSN-Networks Kilian Brunner, ZHAW, Zurich University of Applied Sciences	GCF Certification of Remote SIM Provisioning for Devices with IoT eSIM Lars Skjold Nielsen, Global Certification Forum	Optimizing Boot Time for Embedded Linux Systems Performance Frederic Hoerni, The Embedded Kit by WITEKIO		Mind the Economic Safety Gap: Accelerating Safety Innovation using Generative Artificial Intelligence Andreas Kreutz, Fraunhofer IKS
14:15-14:30	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A		Discussion/Q&A
Coffee Break					
	1.6: TSN Synchronization	1.15: Mesh Networks	2.6: Yocto Use Cases 		3.6: Efficient Engineering of Safety/Security Projects 2
15:00-15:30	Clock Manager: Revolutionizing Industrial Clock Synchronization with Real-Time Monitoring Jun Ann Lai, Intel	Self-Organizing Mobile Mesh Network Torsten Ohlenforst, Fraunhofer IIS	Application Integration on Yocto-based Linux Systems Pierre Gal, The Embedded Kit		Developing Safety Systems with Agile Methods Andre Schmitz, Green Hills Software
15:30-16:00	5G TSN Integration: Achieving Nanosecond-Level Time Synchronization Accuracy for Time-Critical Applications Weifeng Voon, Intel Microelectronics	Off-Grid Emergency Mesh: IoT-Enabled Meshtastic Networks for First Responders Channa Samynathan, Amazon Web Services	Building Yocto-based Linux Systems for Medical Device Compliance Pierre Lecomte, Witekio		A Model-based Approach to Safety-critical Automotive Systems Dr. Bernhard Kaiser, Ansys Germany
16:00-16:30	Time Synchronization over Network Redundancy in Real-Time Applications Daolin Qiu, Texas Instruments	Holistic Framework for LPWAN Protocol Development Johannes Neyer, ZHAW Institute of Embedded Systems	Unlocking Secure OTA Updates for IoT at Scale with Yocto and Containerization Raul Muñoz, Foundries.io		Open Source Software in Safety-Critical Applications: Challenges and Collaborative Solutions Philipp Ahmann, ETAS (BOSCH)
16:30-16:45	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A		Discussion/Q&A

4. HARDWARE DESIGN	5. SOFTWARE & SYSTEMS ENGINEERING	6. EMBEDDED VISION	7. EDGE AI
4.6: RISC-V Development Ecosystem 	5.4: Robust Software Architectures	6.2: Embedded Vision Use Cases 	7.4: Hardware for Edge AI
Moving to RISC-V: Is it Really that Difficult? Designing Software to be Futureproof Hugh Breslin, Microchip Technology	The Role of Reusable Software Components in Safety-Critical Software Development Ehsan Salehi, LDRA	YOLOX Networks in Embedded Vision: Novel Tiled Training and One-Shot Inference for Small Object Detection, Quality Inspection, and Deployment Marco Roggero, The MathWorks	Channeling AI to Revolutionize Semiconductor Dynamics Dr. Marco Addino, Accenture
Transforming the RISC-V Landscape: The Path to Ecosystem Alignment Angel Berrio, Quintauris	From Defense to Offense: A Paradigm Shift in Error Handling Tyler Hoffman, Memfault	Qualification of AI for Embedded Systems Testing: Accelerating DevSecOps Workflows Rainer Poisel, honeytreeLabs	Multi-die Design for Edge AI Applications Hezi Saar, Synopsys
How to Enable RISC-V Processor Customization without Re-verifying the Whole Processor Dr. Zdenek Prikrly, Codasip	Embedded Software Development for Complex System-on-Chip (SoC) Architectures Marcus Nissemark, Green Hills Software	Software Integration Testing for Functional Safety Jeffrey Fortin, Vector Informatik	Multi-instance Machine Learning Models on Limited Hardware Resources Bartosz Boryna, STMicroelectronics
Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A
Lunch Break			
4.7: RISC-V System Design 	5.5: Artificial Intelligence (AI) Algorithms	6.3: AI in Embedded Vision Applications 	7.5: Frameworks for Edge AI
CVA6 MMU-less Virtualization – From Hardware to Software, and Vice Versa! Dr. Sandro Pinto, Universidade do Minho / Zero-Day Labs	Optimizing Implementation of AI Algorithms in Automotive Products Petri Solanti, Siemens EDA	Why Model Based Development Alone is not Sufficient to Ensure Safety and Security in Critical Embedded Software? Mark Richardson, LDRA	Bringing Machine Learning to Embedded Devices with ExecuTorch Christopher Seidl, Arm
Wearable Biomarker Processing using Speckle Plethysmography Based on an Embedded RISC-V ASIP Carsten Rolfes, Fraunhofer IMS	Ensuring Safety in AI/ML-Driven Embedded Systems Ricardo Camacho, Parasoft	Virtual ECUs: Redefining Scalability and Efficiency in Embedded Software Development, Debugging and Testing Matthias Scheid, TASKING Germany	Bridging the TinyML Language Gap with MicroPython and Emlearn Jon Nordby, Soundsensing
The Benefit of RISC-V for Machine Learning Applications Itai Yarom, MIPS	Using Intermediate Representations to Comprehend Embedded Software and Power Retrieval Augmented Generation Daniel Hensley, Driver AI	Importance of Control Coupling Analysis in Certifying Safety Multicore Systems Ehsan Salehi, LDRA	Tiny AI for Safety-Critical Embedded Systems Jonas Messner, Robert Bosch
Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A
Coffee Break			
4.8: Memory: Test for Zero Defect	5.6: Debugging Software & Systems	6.4: Embedded Vision Interfaces	7.6: Smart Sensing Based on Edge AI
An Easy RTL Approach to Boost up IP Subsystem Scan Test Coverage Shanshan Zhou, Synopsys	Comparing Debugging Strategies to Enhance System Reliability Dr. Carmelo Loiacono, Green Hills Software	Kamaros – The Embedded Camera Open API Standard from Khronos Naushir Patuck, Raspberry Pi	Sensor Hub for Near-Sensor Low-latency Data Fusion in AI System Dr. Hoon Choi, Lattice Semiconductor
Silent Data Corruption (SDC) and No Trouble Found (NTF): Ways of Improving Industrial Semiconductor Test Towards 0ppm Prof. Dr. Peter Poechmueller, Neumonda	Highest Availability Needs In-field Debugging Dr. Albrecht Mayer, Infineon Technologies	Migrating to COM Express for Rapid NPI Jeff Baldwin, Sealevel Systems	AI-based IoT Sensors with Autoencoders Kolja Bohne, SSV Software Systems
Errors to Avoid to Ensure Your Storage Media Lasts as Long as Your Device Thom Denholm, Tuxera	Everything You [N]ever Wanted to Know About Hardware Tracing – Utilizing Your Microcontroller's Trace Capabilities for Maximum Timing Insights Harald Paschke, TASKING Germany	Precision Time Synchronization over MIPI Interfaces (Case Study) Roman Mostinski, Mobileye	Where Analog Signal Chains Meet the AI World Dr. Andrei Cozma, Analog Devices
Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A

Want more? See page 7 for additional classes!

2. Embedded OS	3. SAFETY & SECURITY	4. HARDWARE DESIGN	4. HARDWARE DESIGN	5. SOFTWARE & SYSTEMS ENGINEERING
3. SAFETY & SECURITY	4. HARDWARE DESIGN	4. HARDWARE DESIGN	5. SOFTWARE & SYSTEMS ENGINEERING	7. EDGE AI
2.7: Optimization of Embedded OS	3.7: Developing Safe Software	4.9: Developing Embedded Hardware	4.11: Measuring Power Supply Current	5.7: MISRA SW Coding Guidelines 
An Approach to a Maintainable OS-solution Based on Embedded Linux, Safe and Secure Dr. Michael Armbruster, emlix	Debunking the Myth: How, Why, and When CPU Self Test Libraries Boost Microcontrollers Safety Alessandro Bastoni, STMicroelectronics	Design of a Surface-Mounted Qi-Compliant Wireless Power Coil Tobias Egerland, Würth Elektronik eiSos	Growing Significance of Battery-less BLE and its IoT Use Cases Jay Nagdeo, ACAL BFI	MISRA – What's New and What's Happening? Andrew Banks, MISRA and LDRA
Bringing High-End Memory Management to MCUs: Shared Objects for Resource-Constrained Systems Anders Lundgren, IAR Systems	Methods for Integrating Software-Test Libraries in Microcontroller Hypervisors Dr. Andrew Coombes, Arm	Deploying Simscape Electrical Models on FPGAs for HIL Testing Dimitri Hamidi, The Mathworks	IoT Node Powered by TEG in Tree-Air Configuration: 4 Years Results Manuel Böbel, University of Applied Sciences, ZHAW-InES	C, Rust, C-rusted and MISRA for Safe and Secure Embedded Software Prof. Dr. Roberto Bagnara, University of Parma / BUGSENG
Boot Time Optimization for Early Display and Graphics in Embedded Systems Divyansh Mittal, Texas Instruments	Accelerating Safety-Critical Development with Low-Code State Machine Design Anders Holmberg, IAR Systems	Why are 5-Volt Designs Still Relevant? Odd Jostein Svendsli, Microchip Technology	Innovative Battery Fuel Gauging Solution for Ultra-Low Power Applications Steve Harrell, NXP Semiconductors	Iron Carbide: Applying MISRA Rules to C and Rust in Practice Alex Celeste, Perforce Software
Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A
Coffee Break				
3.8: The Way to Safe AI	4.10: Sensors, Actuators, Radar	4.12: Ultra Low Power & Energy Harvesting	5.8: Static Code Analysis	7.7: Edge AI Case Studies 1 
Possibilities on How to Integrate AI in Safety (Embedded) Systems Frank Poignée, infoteam Software	A Low-power DAC Sub-system for Digital Beam Forming Ankur Bal, STMicroelectronics	Streamlining Load Transient Test Setups Xinlei Tang, NXP Semiconductors	Static Analysis – Getting It Right Andrew Banks, LDRA	A Reinforcement Learning Based Controller for Shape Memory Alloy Valves Bryan Marcos Ramos Maldonado, Hahn-Schickard Gesellschaft für Angewandte Forschung e.V.
Can AI Applications be Functionally Safe? Jill Britton, Perforce Software	Faster Time to Market, Effective mmWave Radar Prototyping: A Unified Approach with TI MMIC and MATLAB Matthieu Chevrier, Texas Instruments; Ahmad Saad, Mathworks	Ultra Low Power Leak Detect Odd Jostein Svendsli, Microchip Technology	Challenges in Code Coverage Analysis for Safety-Critical C++ Applications Prof. Dr. Marcel Beemster, Solid Sands	AI Assisted Motor Control: From Simulation to Silicon on a RISC-V with AI Accelerator Steven Klotz, Infineon Technologies
A Workflow for Safe-AI Suzana Veljanovska, Zurich University of Applied Sciences (ZHAW)	A New Experience of Sound – How MEMS Microspeakers and Bone Conduction Sensors Redefine the Listening Experience Dr. Christina Strohrmann, Bosch Sensortec	Ultra-low Noise Wide Bandwidth Current Readout in CMOS Integrated Circuits Dr. Mohammad Amayreh, Hahn-Schickard Gesellschaft für Angewandte Forschung e.V.	Sound Signal Flow Analysis for C/C++ Dr. Daniel Kästner, AbsInt Angewandte Informatik	GPU Based Audio Processing Platform with AI Audio Effects Simon Schneider, Zürich University of Applied Sciences (ZHAW)
Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A	Discussion/Q&A
Lunch Break				
2.10: Embedded OS in Automotive Applications	3.9: Safety & Security Use Cases		5.9: How to Leverage AI for Development	7.8: Edge AI Case Studies 2 
An Open Source Automotive Middleware Stack for Secure and Real-Time Embedded Systems Lars Bauhofer, Qorix	Unified Safety & Security Verification in Automotive Rolland Dudemaine, TrustInSoft		GenAI – The 5th Industrial Revolution and its Impact on How to Share Technical Information Jürgen Mayer-Zintel, Infineon Technologies	Achieving Dependability of AI Execution with Radiation-Hardened Processors Carlos Rafael Tordoya Taquichiri, Zürich University of Applied Sciences (ZHAW)
Navigating the Software Ecosystem for Software-Defined Vehicles: A Multi-OS Architecture Approach Himanshu Pande, Wind River	Mitigating Automotive Cybersecurity Risks in Software Containers for SDVs Gregor Knappik, VicOne		AI-assisted Programming in Embedded Development: A Comparative Study of Human and AI-assisted Engineering Work Dr. Patrick Ott, ERNI Deutschland	Advances in Software Approaches to Execute AI/ML Inference for High-Reliability Applications on Resources Constrained Hardware Dr Pablo Ghiglini, Klepsydra Technologies
Zephyr Usage in Arm Automotive Solutions Software Stack Ed Doxat, Arm	Implementation of CHERI Capabilities in a Safety-critical Real-time Operating System and Type-1 Hypervisor for Intelligent Edge Systems Dmitriy Yeliseyev, Wind River		Accelerating Coding Standards Compliance using AI-augmented Static Analysis Arthur Hicken, Parasoft	Case Study of an Embedded Volume Determination Andy Walter, Cloudflight Germany
Discussion/Q&A	Discussion/Q&A		Discussion/Q&A	Discussion/Q&A